## Technical Note No. 29*

## Options, Futures, and Other Derivatives John Hull

## Proof of Extensions to Ito's Lemma

Options, Futures and Other Derivatives proves Ito's lemma for a function of a single stochastic variable. Here we present a generalized version of Ito's lemma for the situation where there are several sources of uncertainty.

Suppose that a function, $f$, depends on the $n$ variables $x_{1}, x_{2}, \ldots, x_{n}$ and time, $t$. Suppose further that $x_{i}$ follows an Ito process with instantaneous drift $a_{i}$ and instantaneous variance $b_{i}^{2}(1 \leq i \leq n)$, that is,

$$
\begin{equation*}
d x_{i}=a_{i} d t+b_{i} d z_{i} \tag{1}
\end{equation*}
$$

where $d z_{i}$ is a Wiener process $(1 \leq i \leq n)$. Each $a_{i}$ and $b_{i}$ may be any function of all the $x_{i}$ 's and $t$. A Taylor series expansion of $\Delta f$ gives

$$
\begin{equation*}
\Delta f=\sum_{i=1}^{n} \frac{\partial f}{\partial x_{i}} \Delta x_{i}+\frac{\partial f}{\partial t} \Delta t+\frac{1}{2} \sum_{i=1}^{n} \sum_{j=1}^{n} \frac{\partial^{2} f}{\partial x_{i} \partial x_{j}} \Delta x_{i} \Delta x_{j}+\frac{1}{2} \sum_{i=1}^{n} \frac{\partial^{2} f}{\partial x_{i} \partial t} \Delta x_{i} \Delta t+\cdots \tag{2}
\end{equation*}
$$

Equation (1) can be discretized as

$$
\Delta x_{i}=a_{i} \Delta t+b_{i} \epsilon_{i} \sqrt{\Delta t}
$$

where $\epsilon_{i}$ is a random sample from a standardized normal distribution. The correlation, $\rho_{i j}$, between $d z_{i}$ and $d z_{j}$ is defined as the correlation between $\epsilon_{i}$ and $\epsilon_{j}$. In the book's proof of Ito's lemma when there is only one stochastic variable it was argued that

$$
\lim _{\Delta t \rightarrow 0} \Delta x_{i}^{2}=b_{i}^{2} d t
$$

Similarly,

$$
\lim _{\Delta t \rightarrow 0} \Delta x_{i} \Delta x_{j}=b_{i} b_{j} \rho_{i j} d t
$$

As $\Delta t \rightarrow 0$, the first three terms in the expansion of $\Delta f$ in equation (2) are of order $\Delta t$. All other terms are of higher order. Hence

$$
d f=\sum_{i=1}^{n} \frac{\partial f}{\partial x_{i}} d x_{i}+\frac{\partial f}{\partial t} d t+\frac{1}{2} \sum_{i=1}^{n} \sum_{j=1}^{n} \frac{\partial^{2} f}{\partial x_{i} \partial x_{j}} b_{i} b_{j} \rho_{i j} d t
$$

This is the generalized version of Ito's lemma. Substituting for $d x_{i}$ from equation (1) gives

$$
\begin{equation*}
d f=\left(\sum_{i=1}^{n} \frac{\partial f}{\partial x_{i}} a_{i}+\frac{\partial f}{\partial t}+\frac{1}{2} \sum_{i=1}^{n} \sum_{j=1}^{n} \frac{\partial^{2} f}{\partial x_{i} \partial x_{j}} b_{i} b_{j} \rho_{i j}\right) d t+\sum_{i=1}^{n} \frac{\partial f}{\partial x_{i}} b_{i} d z_{i} \tag{3}
\end{equation*}
$$

[^0]For an alternative generalization of Ito's lemma suppose that $f$ depends on a single variable $x$ and that the process for $x$ involves more than one Wiener process:

$$
d x=a d t+\sum_{i=1}^{m} b_{i} d z_{i}
$$

In this case

$$
\begin{gathered}
\Delta f=\frac{\partial f}{\partial x} \Delta x+\frac{\partial f}{\partial t} \Delta t+\frac{1}{2} \frac{\partial^{2} f}{\partial x^{2}} \Delta x^{2}+\frac{1}{2} \frac{\partial^{2} f}{\partial x \partial t} \Delta x \Delta t+\cdots \\
\Delta x=a \Delta t+\sum_{i=1}^{m} b_{i} \epsilon_{i} \sqrt{\Delta t}
\end{gathered}
$$

and

$$
\lim _{\Delta t \rightarrow 0} \Delta x_{i}^{2}=\sum_{i=1}^{m} \sum_{j=1}^{m} b_{i} b_{j} \rho_{i j} d t
$$

where as before $\rho_{i j}$ is the correlation between $d z_{i}$ and $d z_{j}$ This leads to

$$
\begin{equation*}
d f=\left(\frac{\partial f}{\partial x} a+\frac{\partial f}{\partial t}+\frac{1}{2} \frac{\partial^{2} f}{\partial x^{2}} \sum_{i=1}^{m} \sum_{j=1}^{m} b_{i} b_{j} \rho_{i j}\right) d t+\frac{\partial f}{\partial x} \sum_{i=1}^{m} b_{i} d z_{i} \tag{4}
\end{equation*}
$$

Finally consider the more general case where $f$ depends on variables $x_{i}(1 \leq i \leq n)$ and

$$
d x_{i}=a_{i} d t+\sum_{k=1}^{m} b_{i k} d z_{k}
$$

A similar analysis shows that

$$
\begin{equation*}
d f=\left(\sum_{i=1}^{n} \frac{\partial f}{\partial x_{i}} a_{i}+\frac{\partial f}{\partial t}+\frac{1}{2} \sum_{i=1}^{n} \sum_{j=1}^{n} \frac{\partial^{2} f}{\partial x_{i} \partial x_{j}} \sum_{k=1}^{m} \sum_{l=1}^{m} b_{i k} b_{j l} \rho_{k l}\right) d t+\sum_{i=1}^{n} \frac{\partial f}{\partial x_{i}} \sum_{k=1}^{m} b_{i k} d z_{k} \tag{5}
\end{equation*}
$$


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